

Communication System For Ship Using Android App and Wi-Fi

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Abstract—This paper discusses Communication system for ship using Wi-Fi module and Android app. It mainly consists of two parts, Main module in Ship and Module at control room of a Ship like Geographical location like latitude and longitude Position of Ship for tilt towards right in degree, tilt towards left in degree, tilt forward in degree, tilt backward ward in degree. Fuel leakage. Fire detection in cabin. Ship Control in F-Forward, Backward, Right and Left. This information is sent to control room and harbor at 2.4 GHz frequency modulated with FSK. If fire or fuel leakage is detected, it is intimated by audio announcement, displayed on LCD and LED indication. At the control room this all information is received through Wi-Fi modem(IOT) and displayed on Mobile Commands from Mobile issued to control the ship)

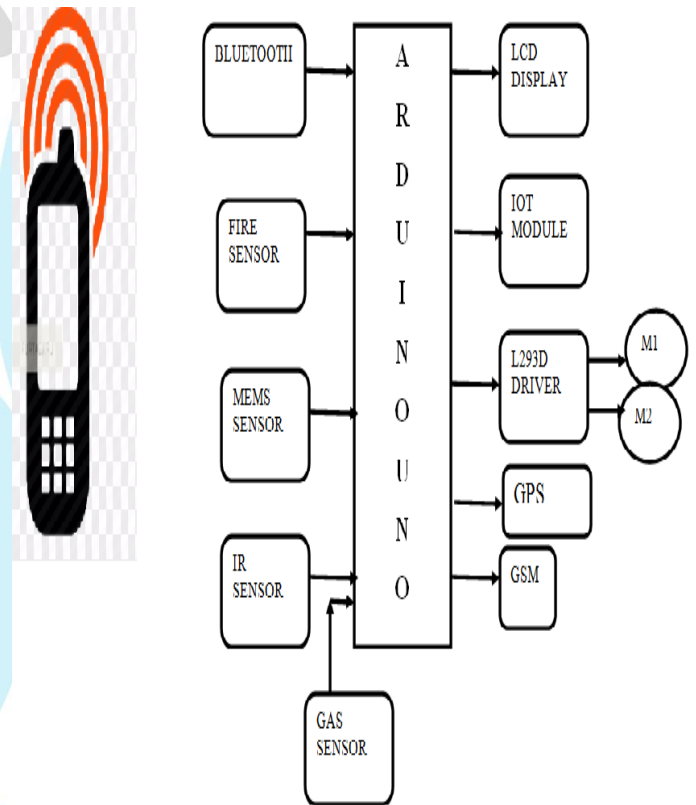
Keywords—IOT: Internet of things, FSK: Frequency shift keying, Wi-Fi module: ESP 89, LED: Light emitting diode.

I. INTRODUCTION

In Correspondence Frameworks for deliver using Wi-Fi and versatile application venture, one can get(controlling unit) valuable information regarding ship with a specific end goal to control the ship right way and furthermore to get mindful about likely mishaps, that is the reason one can maintain a strategic distance from such mischances and furthermore get informed about ship current area. definite information of general task of framework and diagram of activity of route and correspondence arrangement of ship is discussed in this paper with a specific end goal to get saw about information one need to choose important subsection. Ship control is the best most need in the task. Till before couple of years paddles were utilized and one could take the assistance of stars for route. Afterward, the steering haggles came. And after that pilot and route graphs were utilized for determination of the area. This was the general trip of changes to get information of current area of ship and for route. Be that as it may, every one of the traps which were utilized as a part of the past are not as dependable as much as what we utilize today.

Here we utilized the Wi-Fi module ESP 89. To think about sensor signals where it is on or off and utilized Bluetooth display. For to control move course Bluetooth display bolsters android form so we can control deliver utilizing android portable. At that point we utilized MEMS sensors, it is a 3 pivot accelerometer for tilt control. IR sensor is an infrared sensor used to recognize the obstructions. Gas sensor sense the fire of Gas and recognize the spillage of fuel. GPS

demonstrates ebb and flow area of ship then GSM module is utilized to think about ship ebb and flow position and in addition sensors is enacted or not by utilizing versatile SMS office and L293D driver is utilized to drive engine M1 and M2 of ship here we utilized two engines this are lasting attractive DC engines.



Figure(1) – Block Diagram

II. LITERATURE REVIEW.

1. Smart Sailing Robot For Oceanographic Research

Author :- 1Sonali R. Deshpande, 2Anuradha L. Borkar

Over the previous decade there has been extraordinary logical work on self-governing cruising robots. As equipment gets littler, less expensive and furthermore better playing out the conceivable outcomes increment for self-governing vessels.

As of late there is a ton of research going ahead with the point of diminishing CO2 discharges. Brilliant cruising robot fit splendidly into these aspirations. A mechanical sailboat can explore consequently with no human control. The optima course is ascertained which are subject to vital objectives and climate conditions. Rudder and sails are self-sufficiently controlled all together. A self-ruling sailboat must react rapidly changing ecological conditions as sailboats works in exceedingly unique condition. The information which get from sensors must be dissected well for all time by savvy control systems.

2. Ocean sampling and surveillance using autonomous sailboats

Author :-Nuno A. Cruz, Jose C. Alves

This paper comprise of the potential utilizations of little scale cruise water crafts. The utilization of self-ruling sailboats for sea inspecting has been likely proposed previously, yet there was a next to zero consideration from mainstream researchers. There have additionally been minor endeavors towards the improvement and sending of genuine models, because of a portion of the specialized restrictions and huge dangers of activity. Presently right now, the majority of the restrictions have been outperformed, by a few upgrades like the current accessibility of to a great degree low power hardware, adaptable computational frameworks and superior inexhaustible power sources, by doing this, a portion of the real dangers have been alleviated, enabling this rising innovation to wind up a compelling instrument for an extensive variety of utilizations in genuine situations.

III. PROPOSED SYSTEM

To begin with is a controlling of the ship, as we are getting data about current area of ship, its longitude, scope et cetera, we can control the ship through portable application regardless of from wherever we are on the planet as we are utilizing IOT here. Second and most vital part is the wellbeing of ship. Obhviously wellbeing is an excess of vital factor in deliver. On the off chance that we come to think about mischances which can occur in inside a few hours we can control it, that is the reason we get such data through sensors to portable application or it can be shown in plain view in send. By taking a gander at this show data anybody can make fast move so as to counteract mischances.

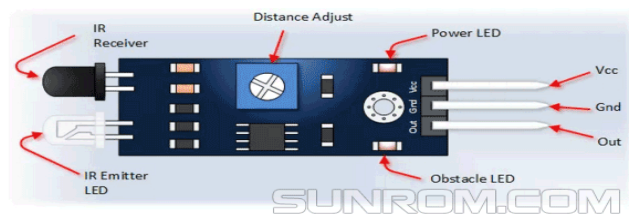
LPG sensor: These days, security is the significant issue in numerous fields because of burglaries, fire mischances and impacts because of LPG gas spillage. At display, LPG gas can be utilized as a part of the auto, in the capacity tank or administration station. Be that as it may, because of a few reasons the LPG gas may spill from the gas barrels, this may cause the chamber impact, harm the house and danger of an existence to the living people in the house. The fire touch off can be happened because of numerous reasons, for example, an electrical short out, oil lights or candles kept inside the house. Now and again fire mischances are little, yet in the

event that appropriate move isn't made to control the fire, at that point it can spread in total house.



Figure(2): LPG sensor

IR sensor: An infrared sensor is an electronic gadget, that produces with a specific end goal to detect a few parts of the environment. An IR sensor can quantify the warmth of a protest and in addition distinguishes the movement.



Pin, Control Indicator	Description
Vcc	3.3 to 5 Vdc Supply Input
Gnd	Ground Input
Out	Output that goes low when obstacle is in range
Power LED	Illuminates when power is applied
Obstacle LED	Illuminates when obstacle is detected
Distance Adjust	Adjust detection distance. CCW decreases distance. CW increases distance.
IR Emitter	Infrared emitter LED
IR Receiver	Infrared receiver that receives signal transmitted by Infrared emitter.

Figure(3): IR sensor

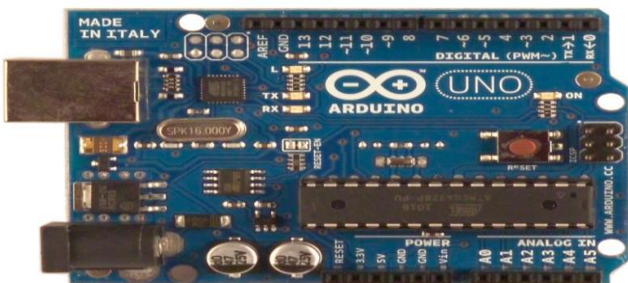
Fire sensor: The Fire sensor is utilized to distinguish fire flames . The module makes utilization of Flame sensor and comparator to identify start up to a scope of 2 ft. This module is touchy to the fire and radiation. It likewise can identify standard light source in the scope of a wavelength 760nm-1100 nm. It can be utilized as a fire alert or in firefighting robots. The module is touchy to the fire and radiation. Fire sensor works by distinguishing infrared radiation produced from flame. The finder identifies this radiation and believes it into simple and advanced signs for the microcontroller to process.



Figure(4): Fire sensor

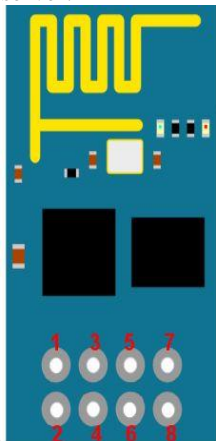
IV. IMPLEMENTATION

In this system arduino uno is used as a controller which is a microcontroller board in light of the ATmega328. It has 14 computerized input/output pins of which 6 can be used as PWM yields, 6 simple inputs, a 16 MHz fired resonator, a USB association, a power jack, an ICSP header, and a reset catch.



Figure(5):Arduino uno

IOT module used to update data related to the sensor on web server.



ESP8266 Pins

1. GND - Circuit Ground
2. TX - UART0 Transmit
3. GPIO2 - General Purpose I/O
4. CH_EN - Chip Enable, Active High
5. GPIO0 - General Purpose I/O
6. RESET - Reset, Active Low
7. RX - UART0 Receive
8. VCC - Circuit Power = +3.3V DC

Figure(6)ESP8266

Different sensors are used like MEMS sensor, IR sensor, fire sensor, gas sensor, by utilizing Bluetooth module to control

the ship naturally. HC-05 installed Bluetooth serial correspondence module is used. At the point when the module is at the programmed association work mode, it will take after the default way set ultimately to transmit the information consequently. At the point when the module is at the request reaction work mode, client can send the AT summon to the module to set the control parameters and sent control arrange. In the event that any sensor is identified then IOT module used to refresh information on web server.

Also, lcd show will show all data identified with the sensor. Mems sensor distinguish a movement , IR sensor identify a deterrent, fire sensor recognize fire, and gas sensor used to recognize a gas level in condition.

V. CONCLUSION

We intend to convey and control dispatch utilizing Wi-Fi and Android Application at last anyone can work deliver utilizing cell phones, so there is no need of practice individual to drive send for security reason we included Fire sensors, fuel spillage sensor, IR sensor, Signal along these lines we will avert such mischances in a ship and GPS will give the present position of a ship. In a ship when impediments are happened before transport at that point ship will be naturally ceased, in this way mischances won't occur. We reason that by utilizing Android application IOT module diverse sensors, ship can work effortlessly.

VI. FUTURE WORK

We will include camera in a ship for to work dispatch with no human obstruction inside a ship. Because of camera administrator can see ships current circumstance and it can be controlled ship effectively and it will avert such mishap. We can add sun powered board for to supply vitality to the ship, with the goal that numerous costs on a fuel of ship can get decreased. Additionally the contamination get diminished because of utilization of sunlight based boards. For putting away vitality we will include the rechargeable batteries that will be get charged utilizing sun based vitality and additionally electric vitality. For self preservation we can include consequently worked weapons, for example, assault rifles, bombs and so on. For to perceive approved individual we can include confront identification framework in a ship.

VII. REFERENCES

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